# GRASPING PROTOCOL

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| Purpose | To test successful grip of a object set inspired by activities of daily living (ADL) |
| Task Description | Pick up, Hold 5s, Controlled Rotation 180°, Controlled put down in initial pose |
| Constrains | Maximum 10 tries for grasping successfully/ Grasping until first success. |
| Object set | Subset of YCB object set |
| Subject/ Operator Description | The person with the maximal expertise in using the prosthesis |

ID 1:

| YCB ID 6: Master Chef Coffee Can . | Description of the grasping environment: Resting on completely on a solid surface |  |
|---|---|---|
| | Desired Grip: Cylindrical Grip | |
| | Initial poses of the objects: Upright Standing | |

ID 2:

| YCB ID 13: Plastic Apple | Description of the grasping environment: Resting on completely on a solid surface |  |
|---|---|---|
| | Desired Grip: Spherical Grip | |
| | Initial poses of the objects: Upright Standing | |

ID 3:

| YCB ID 27: Spoon | Description of the grasping environment: Laying in the bowl YCB 25 |  |
|---|---|---|
| | Desired Grip: Tripod Pinch | |
| | Initial poses of the objects: Laying concave in the bowl | |

ID 4:

| YCB ID 25: Bowl | Description of the grasping environment: Resting on completely on a solid surface |  |
|---|---|---|
| | Desired Grip: Lateral Pinch | |
| | Initial poses of the objects: Laying concave | |

ID 5:

| | Description of the grasping environment: Resting on completely on a solid surface |
|---|---|
| YCB ID 32: Skillet | Desired Grip: Diagonal Volar Grip |
| | Initial poses of the objects: Laying concave |



ID 6:

| | Description of the grasping environment: Resting on completely on a solid surface |
|---|---|
| YCB ID 37: Small Marker | Desired Grip: Pulp Pinch |
| | Initial poses of the objects: Laying |



ID 7:
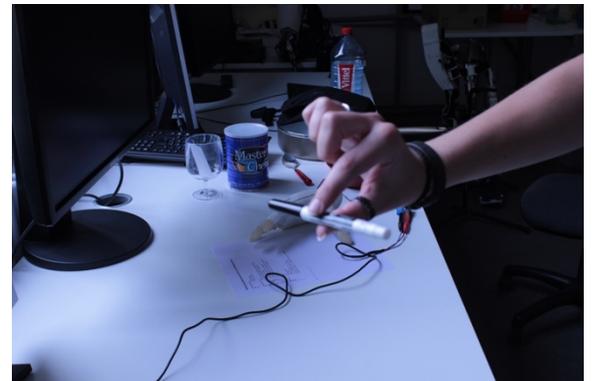
| | Description of the grasping environment: 80% on a solid surface, 20% hanging of the table edge |
|---|---|
| YCB ID 75: Black Tshirt | Desired Grip: Extension Grip |
| | Initial poses of the objects: Laying on the surface, folded |



ID 8:

| | Description of the grasping environment Resting on completely on a solid surface |
|---|---|
| YCB ID 33: Skillet Lid | Desired Grip: Hook |
| | Initial poses of the objects: Laying convex |